Robots, Unions, and Aging Determinants of Industrial Robot Adoption: Evidence from OECD Countries

Donato Onorato

University of Pennsylvania

October 13, 2018

Contents

O [Introduction](#page-1-0)

[Model](#page-8-0)

[Data](#page-17-0)

[Empirical Specification](#page-21-0)

[Results](#page-33-0)

[Conclusion](#page-43-0)

Widespread belief that robots will take the jobs of humans

Percentage who say that in the next 50 years robots and computers will "definitely" or "probably" do much of the work currently done by humans.

*U.S. data is from 2015. All other countries show data from 2018.

Source: Pew Research Center

Previous Literature

Graetz & Michaels (2015)

- \triangleright Examine effects of robot adoption on wages and employment
- \triangleright Find that robots increase productivity, wages, growth rate of economies studied

Graetz & Michaels (2015)

- \triangleright Examine effects of robot adoption on wages and employment
- \triangleright Find that robots increase productivity, wages, growth rate of economies studied

Acemoglu & Restrepo (2017)

- \triangleright Examine effect of industrial robots within commuting zones in U.S.
- \triangleright Develop a task based model of robot substitution for labor
- \triangleright Find that an additional robot per worker reduces employment and wages in each commuting zone

Graetz & Michaels (2015)

- \triangleright Examine effects of robot adoption on wages and employment
- \triangleright Find that robots increase productivity, wages, growth rate of economies studied

Acemoglu & Restrepo (2017)

- \triangleright Examine effect of industrial robots within commuting zones in U.S.
- \triangleright Develop a task based model of robot substitution for labor
- \triangleright Find that an additional robot per worker reduces employment and wages in each commuting zone

Acemoglu & Restrepo (2018)

- \triangleright Use small sample cross section data to examine effect of aging on robot usage
- \triangleright Find that older countries adopt more robots and develop robot technologies more intensively

OECD Industrial Robot Stock 2000-2015

Research Question

What economic and demographic features characterize industrial robot adoption?

- \triangleright Can variation in observable characteristics explain some of the differential adoption of robots we observe?
- \triangleright Specifically, focus on how population aging affects equilibrium industrial robot stocks.
- \blacktriangleright I also include union share, income levels, population, and reliance on robot-using industries as features that may partially characterize robot usage rates

O [Introduction](#page-1-0)

² [Model](#page-8-0)

3 [Data](#page-17-0)

4 [Empirical Specification](#page-21-0)

6 [Results](#page-33-0)

6 [Conclusion](#page-43-0)

- \triangleright To motivate my focus on aging and the empirical specification I build a simple two sector model with two types of labor (young and old)
- \triangleright The model incorporates ideas from Acemoglu & Restrepo (2017) and Graetz & Michaels (2015) in a simplified setting
- \triangleright Main idea: Some industries require young labor and when this type labor is scarce firms can substitute with robots. How often this happens depends on the share of the economy that can be automated and the relative price of robots.
- \blacktriangleright I consider a static, frictionless economy
- \triangleright Total labor in the economy is fixed at L and there are two types of workers: young workers (L_Y) and old workers (L_O)
- In There are two sectors in the economy: robot using sector (Y_R) and the non-robot using sector (Y_N)
- Robots are exogenously supplied at price ρ

Sectors of the Economy

 \triangleright For simplicity, the robot using sector combines only young labor and robots in a CES production function to produce Y_R

$$
Y_R = \left[R^{\frac{\sigma - 1}{\sigma}} + L_y^{\frac{\sigma - 1}{\sigma}} \right]^{\frac{\sigma}{\sigma - 1}}
$$

- Here $\sigma > 0$ represents the elasticity of substitution between robots and labor in the robot using sector
- ► As in Acemoglu & Restrepo (2017) and Graetz & Michaels (2015) I allow robots and labor to be substituted imperfectly

Sectors of the Economy

 \triangleright For simplicity, the robot using sector combines only young labor and robots in a CES production function to produce Y_R

$$
Y_R = \left[R^{\frac{\sigma - 1}{\sigma}} + L_y^{\frac{\sigma - 1}{\sigma}} \right]^{\frac{\sigma}{\sigma - 1}}
$$

- Here $\sigma > 0$ represents the elasticity of substitution between robots and labor in the robot using sector
- ► As in Acemoglu & Restrepo (2017) and Graetz & Michaels (2015) I allow robots and labor to be substituted imperfectly
- \triangleright The non-robot using sector uses old labor to produce Y_N

$$
Y_N=L_O
$$

Aggregate Economy

 \triangleright Suppose that the aggregate production of the economy is also given by a CES aggregate over each sector

$$
Y = \left[\gamma_1 Y_R^{\frac{\varepsilon - 1}{\varepsilon}} + \gamma_2 Y_N^{\frac{\varepsilon - 1}{\varepsilon}}\right]^{\frac{\varepsilon}{\varepsilon - 1}}
$$

- \blacktriangleright Here, $\varepsilon > 0$ represents the elasticity of substitution between the outputs of each sector
- \blacktriangleright The γ_i are share parameters measuring the relative importance of each sector in the economy so that

$$
\sum_i \gamma_i = 1
$$

- In this setting I interpret σ as the substitution options between factors (robots, labor) at the task level (as in Acemoglu & Restrepo, 2017)
- I interpret ε as the subtitution possibities between sectors in the economy (as in Graetz & Michaels, 2015)
- In this setting I interpret σ as the substitution options between factors (robots, labor) at the task level (as in Acemoglu & Restrepo, 2017)
- I interpret ε as the subtitution possibities between sectors in the economy (as in Graetz & Michaels, 2015)
- \blacktriangleright I assume that substitution options between industries in aggregate production are more limited than substitution options between robots and labor at the task level

σ > ε

$$
R^{d} \equiv \frac{R}{L} = \left(\frac{1}{\rho}\right)^{\sigma} \left(\frac{\gamma_{2}}{\gamma_{1}}\right)^{\frac{\sigma \epsilon}{\epsilon - \sigma}} \left(\frac{\ell_{y}}{\ell_{o}}\right)^{\frac{\sigma}{\epsilon - \sigma}} \ell_{y}
$$
(1)

- \triangleright Under the elasticity assumption $(σ > ε)$:
- **1** Robot density is decreasing in the price of industrial robots, ρ .
- **2** Robot density is increasing in the share of old workers.
- **3** Robot density is increasing in share parameter γ_1 and decreasing in γ_2

O [Introduction](#page-1-0)

[Model](#page-8-0)

[Data](#page-17-0)

[Empirical Specification](#page-21-0)

[Results](#page-33-0)

[Conclusion](#page-43-0)

I construct a panel data set of 34 OECD countries during the years 2000-2015 from three major sources:

- \triangleright International Federation of Robotics (IFR)
- \triangleright OECD National Account Statistics
- \triangleright OECD Labor Market Statistics
- \triangleright The IFR compiles data from a comprehensive list of worldwide robot suppliers
- \triangleright They provide data on the stocks and flows of industrial robots by sector for a large group of countries
- \blacktriangleright They define an industrial robot as:

"An automatically controlled, re-programmable, multipurpose manipulator programmable in three or more axes, which can be either fixed in place or mobile for use in industrial automation applications."

- \triangleright Data on GDP per capita and the share of workers in a union come from the OECD
- \triangleright Current **population** data and population forecasts come from the UN Population Division World Population Prospects 2017
- \triangleright Data on the share of value added by industry comes from the World Bank's World Development Indicators

O [Introduction](#page-1-0)

[Model](#page-8-0)

[Data](#page-17-0)

[Empirical Specification](#page-21-0)

[Results](#page-33-0)

[Conclusion](#page-43-0)

Based on the model I propose the follow log-log functional form:

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

robot density

$$
\overline{\log(R_{ct}^d)} = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

 \blacktriangleright I define robot density as the number of industrial robots per 10,000 workers

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

I define age ratio as the ratio of young workers (ℓ_Y) to old workers (ℓ_O)

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

- I define age ratio as the ratio of young workers (ℓ_Y) to old workers $(\ell_{\mathcal{O}})$
- \blacktriangleright I define young workers as those aged 15-54 and old workers as those aged $55+$

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

- I define age ratio as the ratio of young workers (ℓ_Y) to old workers $(\ell_{\mathcal{O}})$
- I define young workers as those aged 15-54 and old workers as those aged $55+$
- \blacktriangleright I test the sensitivity of the results to alternate cutoffs

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

 \blacktriangleright I define the **union share** as the share of workers in a labor union

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

- \blacktriangleright I define the **union share** as the share of workers in a labor union
- \blacktriangleright I use this to proxy the level of labor protections that may prevent firms from automating

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \frac{\beta_3 \log(IVA_{ct})}{\beta_3 \log(IVA_{ct})} + \beta_4 \log(X_{ct}) + \varepsilon_{ct}
$$

automation reliance

 \blacktriangleright I measure reliance on automatable industries by the ratio of value added from the automation susceptible industries to value added from the remaining industries of the economy

 \blacktriangleright This appears in the model as the ratio of share paramters γ_i

$\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(A R_{ct}) + \beta_2 \log(UN ION_{ct}) + \sqrt{\beta_3 \log(VNA_{ct})}$ automation reliance $+ \beta_4 \log(X_{ct}) + \varepsilon_{ct}$

- \blacktriangleright I proxy automation susceptible industries with the *industry* sector defined by the World Bank
- \triangleright The *industry* sector is an aggregate of industries including: mining, manufacturing, construction, water, electricity, and gas.

Industrial Robots by Industry

Empirical Specification

$$
\log(R_{ct}^d) = \alpha_c + \mu_t + \beta_1 \log(AR_{ct}) + \beta_2 \log(UNION_{ct}) + \beta_3 \log(IVA_{ct}) + \underbrace{\beta_4 \log(X_{ct})}_{\text{controls}} + \varepsilon_{ct}
$$

 \blacktriangleright I include a set of additional controls for total population and GDP per capita

O [Introduction](#page-1-0)

[Model](#page-8-0)

[Data](#page-17-0)

[Empirical Specification](#page-21-0)

[Results](#page-33-0)

[Conclusion](#page-43-0)

∗Significant at the 10 percent level.

The results are robust to alternate age cutoffs:

- \blacktriangleright I get similar results when I define young and old workers as:
	- \blacktriangleright 20-44, 45-69
	- \blacktriangleright 15-49, 50-69

The results are robust to alternate age cutoffs:

- \blacktriangleright I get similar results when I define young and old workers as:
	- \blacktriangleright 20-44, 45-69
	- \blacktriangleright 15-49, 50-69

The results are also robust to alternate time periods:

- I get similar results when I estimate over the following time periods:
	- \blacktriangleright 2000-2007
	- \blacktriangleright 2008-2015
	- \blacktriangleright 2010-2015

Na¨ıve Predictions

I use the estimates to see what robot stock would be today had the age ratio remained at its 2010 level

Na¨ıve Predictions

I use the estimates to see what robot stock would be today had the age ratio remained at its 2010 level

 \triangleright Age ratio decreased 10% on average among OECD countries from 2010 to 2015.

- \triangleright Age ratio decreased 10% on average among OECD countries from 2010 to 2015.
- \blacktriangleright Had it remained unchanged over that period there would be 25% fewer robots per 10,000 workers on average

- \triangleright Age ratio decreased 10% on average among OECD countries from 2010 to 2015.
- \blacktriangleright Had it remained unchanged over that period there would be 25% fewer robots per 10,000 workers on average

I can also use the estimates to predict 2020 values of industrial robot stock by predicting future values of the covariates & UN population projections

- Age ratio decreased 10% on average among OECD countries from 2010 to 2015.
- \blacktriangleright Had it remained unchanged over that period there would be 25% fewer robots per 10,000 workers on average

I can also use the estimates to predict 2020 values of industrial robot stock by predicting future values of the covariates & UN population projections

 \triangleright On average OECD countries will add 9.95 additional robots per 10,000 workers by 2020

- Age ratio decreased 10% on average among OECD countries from 2010 to 2015.
- \blacktriangleright Had it remained unchanged over that period there would be 25% fewer robots per 10,000 workers on average

I can also use the estimates to predict 2020 values of industrial robot stock by predicting future values of the covariates & UN population projections

- \triangleright On average OECD countries will add 9.95 additional robots per 10,000 workers by 2020
- \triangleright This represents a 1.7x increase from 2015 levels and is primarily driven by aging

O [Introduction](#page-1-0)

[Model](#page-8-0)

[Data](#page-17-0)

[Empirical Specification](#page-21-0)

[Results](#page-33-0)

[Conclusion](#page-43-0)

 \triangleright Union rates and the labor force age ratio have significant negative effects on industrial robot stock even after controlling for population, GDP per capita, and reliance on robot-using industries

Union rates

- \triangleright Union rates may be a signal of labor protection within a country
- \triangleright This could produce a barrier for firms that want to switch from human labor to robots

Aging

Union rates

- \triangleright Union rates may be a signal of labor protection within a country
- \triangleright This could produce a barrier for firms that want to switch from human labor to robots

Aging

- \triangleright Some sectors of the economy may require "young" labor
- If labor and robots are easily substituted $(\sigma > \varepsilon)$, aging shocks to the labor force could force firms to adopt more robots
- \triangleright This aging effect is consistent with previous literature about technological adoption under labor scarcity (see Acemoglu, 2015)